Debugging one API applications with The Intel® Distribution for GDB*



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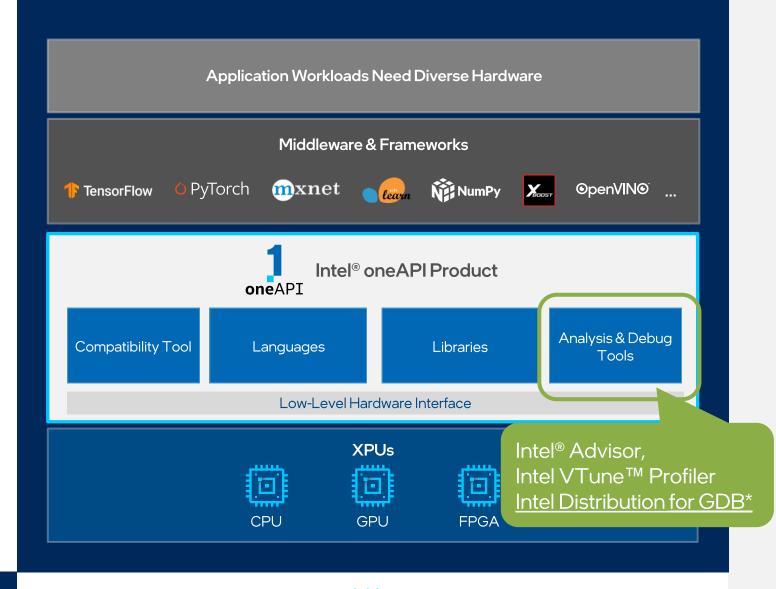
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Intel® oneAPI Product

Built on Intel's Rich Heritage of CPU Tools Expanded to XPUs

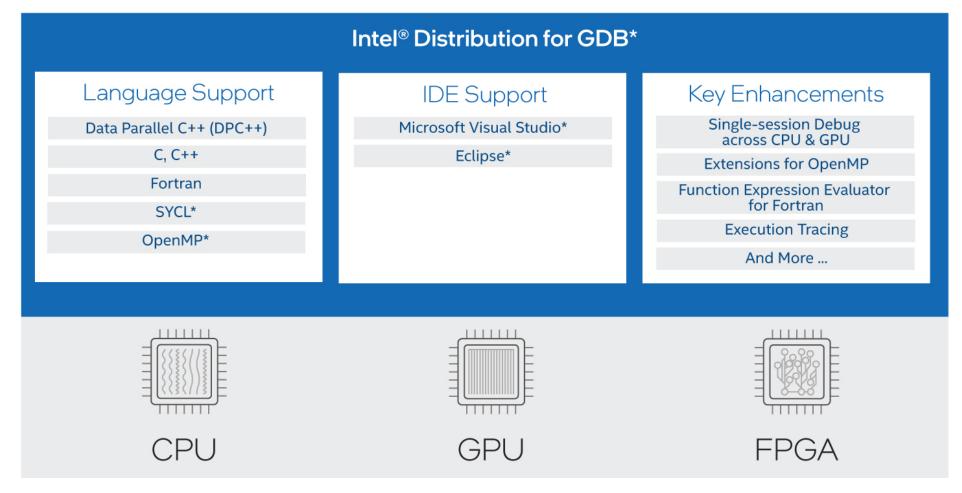
A complete set of advanced compilers, libraries, and porting, analysis and debugger tools

- Accelerates compute by exploiting cutting-edge hardware features
- Interoperable with existing programming models and code bases (C++, Fortran, Python, OpenMP, etc.), developers can be confident that existing applications work seamlessly with one API
- Eases transitions to new systems and accelerators—using a single code base frees developers to invest more time on innovation



Available Now

Overview of Intel® Distribution of GDB



Focus of this workshop is on debugging DPC++ GPU kernels

Setup for GPU (Linux)

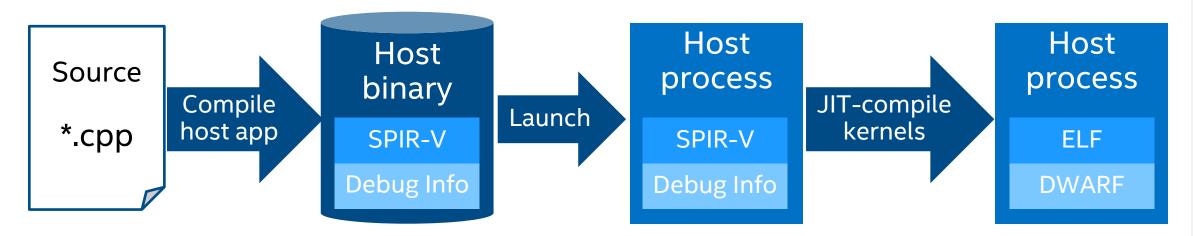
Install the debug companion driver (DCD)

```
$ tree /opt/intel/oneapi/debugger/latest/
    dep
    L— lib
    documentation
                            User Manual
      - gdb.pdf
        info
        man
    env
     - vars.sh
                         Debug driver
    qdb
     - intel64
    igfxdcd-1.8.0-Linux.deb
    igfxdcd-1.8.0-Linux.rpm
```

```
sudo dpkg -i path/to/igfxdcd-1.8.0-Linux.deb
sudo modprobe igfxdcd
```

Additional setup steps maybe necessary, see Get Started guide

Application Compilation (JIT)

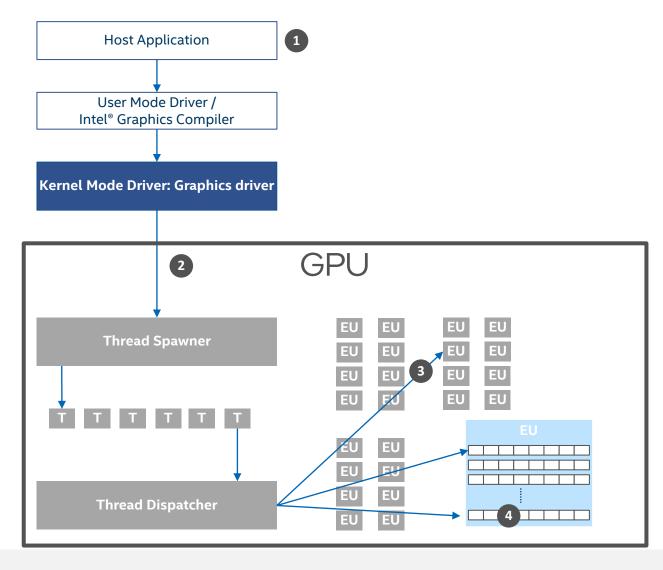


Kernels are translated to SPIR-V IR

- Compile with -g (generate debug information) and -OO (disable optimization) to debug.
 - May use -02 to debug at assembly level
 - Use same optimization level when linking
- Debug also works with ahead-of-time (AOT) compilation

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GPU Debug Model



- Host inferior*
- 2. Device inferior*, one per Device / Tile
- 3. Device thread, one per EU thread
- 4. SIMD lanes, depending on SIMD width (1/8/16/32)
- *inferior ≈ debuggee process

Fundamental GDB Commands

Command	Description
help <cmd></cmd>	Print help info
run [arg1, argN]	Start the program, optionally with arguments
break <file>:<line></line></file>	Define a breakpoint at a specified line
info break	Show defined breakpoints
delete <n></n>	Remove Nth breakpoint
step / next	Single-step a source line, stepping into / over function calls
info args/locals	Show the arguments / local variables of the current function
print <exp></exp>	Print value of expression
x/ <format> <addr></addr></format>	Examine the memory at <addr></addr>
up, down	Go one level up/down in the function call stack
disassemble	Disassemble the current function
backtrace	Show the function call stack

GPU-Relevant GDB Commands

Command	Description
info inferiors	Display information about the inferiors. GPU Debugging will display additional inferior(s) (gdbserver-gt)
info threads <thread></thread>	Display information about threads, including their active SIMD lanes
thread <thread>:<lane></lane></thread>	Switch context to the SIMD lane of the specified thread
thread apply <thread>:<lane> <cmd></cmd></lane></thread>	Apply <cmd> to specified lane of the thread</cmd>
set scheduler-locking on/step/off	Lock the thread scheduler. Keep other threads stopped while current thread is stepping (step) or resumed (on) to avoid interference. Default (off)
set nonstop on/off	Enable/disable nonstop mode. Set before program starts. (off): When a thread stops, all other threads stop. Default. (on): When a thread stops, other threads keep running.
print/t \$emask	Inspect the execution mask to show active lanes

Inferiors

GDB uses *inferior* objects to represent states of program execution (usually a process)

Debugger create inferior(s) that attaches to GPU(s) to receive events

and control the GPU

```
Intel® Distribution for GDB*
Inferior 1 Inferior 2 gdbserver-gt

Debug CPU

Linux native target Remote target Debug GPU
```

Debugging Threaded GPU SIMD Code

Kernel code written for single work-item

- Code implicitly threaded and widened to vectors of work-items
- Variable locations expressed as functions of the SIMD lane
 - Lane field added to thread representation <inferior>.<thread>:<lane>
 - Applies to info threads, thread, thread apply ...

SIMD Lanes Support

Disabled due to SIMD width



if (index % 2 == 0)
 out[index] = value;
else
 out[index] = -value;

-Disabled due to conditional flow

- Only enabled SIMD lanes displayed
- SIMD width is not fixed

A thread might switch between different kernels with different SIMD widths

- A user can switch only between enabled SIMD lanes
- After a stop, GDB switches to an enabled SIMD lane
- If target architecture does not support SIMD or thread SIMD width is 1, GDB behavior is unchanged

A Sample GDB Session

```
$ gdb -q sycl-if
   Reading symbols from sycl-if...
   (qdb) set print thread-events off
   (gdb) break 21
   Breakpoint 1 at 0x40497b: file src/sycl-if.cpp, line 21.
   (qdb) ignore 1 41
   Will ignore next 41 crossings of breakpoint 1.
   (gdb) run
   Starting program: .../sycl-if
  [...]
  intelgt: attached to device with id 0x3ea5 (Gen9)
  intelgt: inferior 2 (gdbserver-gt) created for process 1555133.
   [Switching to Thread 1073746465 lane 1]
  Thread 2.43 hit Breakpoint 1, with SIMD lanes [1 3 5 7], compute(int*, int*)::$ 0::operator()(cl::sycl::handler&)
   const::{lambda(cl::sycl::id<1>)#1}::operator()(cl::sycl::id<1>) const (this=0x2dfff00, index=...) at sycl-if.cpp:21
              out[index] = -value;
  (gdb) list
           cgh.parallel for<class kernel>(range, [=](sycl::id<1> index) {
       int value = in[index];
       if (index % 2 == 0)
  19
           out[index] = value;
  20
          else
              out[index] = -value;
  21
         });
  23
        });
   2.5
  (gdb) print index
  $1 = {<cl::sycl::detail::array<1>> = {common array = {617}}, <No data fields>}
• (gdb)
```

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Multi-Device Debugging

- A program can offload a kernel to all or subset of GPU devices
- Intel® Distribution for GDB* can debug the CPU and GPUs in the same debug session
- User can switch to the context of a thread on a GPU or the CPU
- Each GPU device appears as a separate inferior (i.e. process)
- Inferior for a device does not appear if not used
- Threads of the GPUs can be independently resumed; thread state can be examined.

Multi-Device Debugging

```
-gpu.cpp
                  cl::sycl::device device = devices[device_index];
    31
                  print_device ("Found", device);
    32
    33
    34
                  return cl::sycl::queue {device}; /* return-sycl-queue */
    35
36
    37
                static void
    38
                compute (cl::sycl::id<1> index)
    39
    40
                  int point = index[0];
                  int a = 33; /* kernel-line-1 */
 B+ 41
                  int b = 44:
 B+>43
                  int c = 55: /* kernel-line-3 */
    44
    45
                static void
extended-r Thread 3.1073741824 In: _ztszzL3runRN2cl4sycl5queueEENKUlRNS0_7handlerEE54_24clES4_EUlNS0_2idILi1EEEE* L43
                                                                                                                            PC: 0xffde3640
```

```
\[ \text{Gdb} \] info threads \[ \text{Id} \] \[ \text{Target Id} \] \[ \text{Frame} \] \[ \text{In Target Id} \] \[ \text{Frame} \] \[ \text{In Thread 0x7ffff6e37000 (LWP 401277) "multi-gpu" 0x00007ffff725f89b in sched_yield () \] \[ \text{from /lib/x86_64-linux-gnu/libc.so.6} \] \[ \text{In thread 0x5ffff37c5700 (LWP 401281) "multi-gpu" 0x00007ffff727150b in ioctl () from /lib/x86 64-linux-gnu/libc.so.6} \] \[ \text{2.1:[0-7] Thread 0x5ffff37c5700 (LWP 401281) "multi-gpu" 0x00007ffff727150b in ioctl () from /lib/x86 64-linux-gnu/libc.so.6} \] \[ \text{2.1:[0-7] Thread 2.1073741824} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{3.1:0} \] \[ \text{Thread 3.1073741824} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{3.2:[0-7] Thread 3.1073741888} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{3.2:[0-7] Thread 3.1073741888} \] \[ \text{compute (index=cl::sycl::id<1> = \{...\}) at multi-gpu.cpp:43} \] \[ \text{3.2:[0-7] Thread 3.1073741888} \]
```

Second GPU's threads

First GPU's threads

Host application threads (CPU)

Limitations

- If a bug occurs on both CPU and GPU, debug on the CPU
- Breakpoint must be set inside kernel to debug GPU
 - Unable to step into the kernel, separate inferiors
- Debug process state on hardware (not on CPU)
 - Restricts GPU to single context (unable to perform other tasks)
 - Display interruption for rendering GPU
- CPU polls status of debug process state through MMIO
 - Increases load on host
- See <u>Release Notes</u> for complete list

Case Study: Using Intel® Distribution of GDB* to Debug SYCL ZFP Compression Library

- ZFP: open-source library for compressed floating-point and integer arrays
 - Supports high-throughput random access read and write to individual elements
- Intel® DPC++ Compatibility Tool used to assist the migration of the CUDA source to DPC++
 - Unit test failures for 1D double, 2D float, 2D double, and all 3D cases.
- Intel® Distribution for GDB* used to identify the bug

Debugging ZFP

- Identify indices of the array that was failing
 - Incorrect encoding due to overflow was happening for certain indices
- 2. Start debugger
- 3. Set conditional breakpoint in kernel
 - b encode1.dp.hpp:64 if block_idx==65534
- 4. After stepping through kernel code, an unnecessary typecast from double to float was discovered, causing overflow

References

- Intel® Distribution for GDB* Get Started Guide
 - Linux, Windows
- Debugging with Intel® Distribution for GDB Tutorial
 - Linux, Windows
- Intel® Distribution for GDB* Release Notes
- Intel® Distribution for GDB* Reference Sheet
- Debugger Samples on GitHub

Summary

- Intel® Distribution for GDB* can be used to debug host and device for oneAPI applications written in various languages
- Traditional GDB commands have been extended to accommodate GPU execution model

#